

Notice:

Microbit remote control:

1. The remote control microbit is in the horizontal state, that is, the logo and the two buttons are facing up, zero state, the car stops moving.
2. Trigger from the zero point state, press the logo side down, the car is forward, reverse back; press the button A side, the car moves to the left, and vice versa.
3. Press and hold button A, while remotely swinging the left or right movement gesture, the car state switches to steering (ie, single wheel rotation)
4. Press and hold button B, and remotely swing the left or right movement gesture, the car realizes drifting. At this time, if the body gesture is the front side, the car will drift at the top and bottom, the front wheel will not move, and the drift range is small; At this time, if the somatosensory gesture is the rear side, as the backward gesture gradually becomes larger, the range in which the car drifts is larger, and the front wheel gradually increases in speed.

[Meowbit](#) remote control: (refer to the description of microbit remote control)

1. The left joystick controls the front, rear, left and right and oblique side of the trolley.
2. Button A is still a turning effect, but it should be noted that the direction of turning is only to follow the direction of the rocker before pressing A. After pressing A, the car rotates in a fixed direction, even if the joystick changes direction, the car is in any position. However, it will move in the previous direction. When the button A is released, the joystick value will be re-acquired.
3. Button B is the drift effect, and the method of use is the same as 2.